S2P: a reproducible Satellite Stereo Pipeline

- 1. Description of the s2p software
- 2. Some github "drama" (licensing, collaboration)
- 3. Two forms of reproductibility
 - 3.1. pip install s2p
 - 3.2. online jupyter notebook

THE PROBLEM : COMPUTE 3D MODELS FROM OPTICAL IMAGES

Input: multiple views

Output: 3D reconstruction



Images: WorldView3 from the MVS benchmark dataset of [Bosch et al 2016]

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- * Other users:
 - Random chinese developers asking questions on github
 - Oleg Alexandrov (from NASA)

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* **NASA** : AMES stereo pipeline



* CNESC : CARS+Pandora (used for CO3D) 🖧 pandora



CARS produces a Digital Surface Model (DSM)







SPECIFIC DIFFICULTIES OF SATELLITE STEREO

- * Easy: Single-date image pair from one satellite
- * More than two images: need for a "fusion" strategy
- * Multi-date difficulties (hard matching)
- * Multi-satellite difficulties (super-hard matching)
- * Degenerate bundle adjustment

OVERVIEW OF THE WHOLE PIPELINE



Jérémy: Super-resolution



Carlo: Crop and local RPC refinement



3. Roger: Bundle adjustment



Gabriele: Correlation

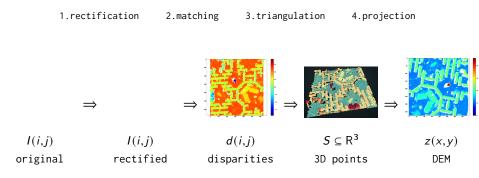


Roger: DEM filtering and fusion



INNER CORE OF THE PIPELINE

Four steps to convert a pair of images to a DEM:



- 1. Find industrial partners with exciting new problems
- 2. Refactor legacy parts of the code
- 3. Try/develop GPU-based correlators
- 4. (Optionally) integrate single-image 3D methods

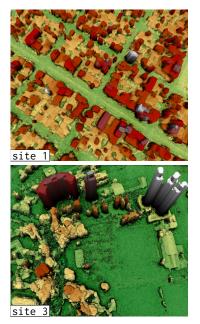


texturing by simple averaging

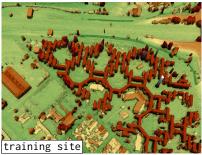


texturing with shadow removal

S2P OUTPUT RESULTS







(browse github repo, issues, etc)

github.com/cmla/s2p

Three independent issues:

- 1. Licensing (AGPL, GPL, MIT, Apache, BSD, dual)
- 2. Contribution license agreement
- 3. Contribution guidelines

The most critical decision is probably the CLA, and it is nearly impossible to change later on. Copyright holders can agree to change the license as they want.